

Memory saving for neural network trainng

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Introduction



- Rotor: Rematerializing Optimally with pyTORch
 - Efficient with sequential models



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- Weight Offloading
 - Non-optimal but efficient



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 - Efficient with sequential models
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 - Non-optimal but efficient
- Rotor+checkmate(Ongoing)
 - Combined ideas to be general and efficient





Weight offloading



Possibility of training large model in a single GPU

Only keep what is necessary



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Forward *i*

•
$$a^i \leftarrow a^{i-1}, w_i$$

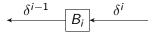




Training iteration

Backward *i*

- $\delta w_i \leftarrow a^{i-1}, \delta^i$;
- $\delta^{i-1} \leftarrow \delta^i$, w_i ;
- $w_i \leftarrow w_i, \, \delta w_i$





Offload layers that cover most memory needs

Greedy selection

- Assume infinite bandwidth
- Start: every layer in GPU
- Choose w_i that covers the most memory overflow
- Iterate until memory fits
- A coefficient is introduced for single offloading



Greedy schedule

- Insert prefetch and offload operations into F's and B's
- Data required earlier is prefetched first
- Data produced earlier is offloaded first
- One particular case: *w_i* is sent to CPU after *B_i*, but only deleted after *F_i*



Simulation results

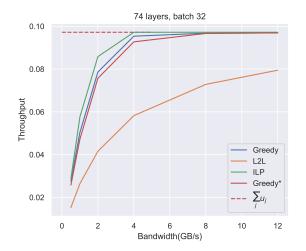


Figure: Greedy* represents the Greedy algorithm while weights are not only offloaded once.





Rotor+checkmate



Checkmate provides an optimal solution for rematerializations.

Application

- Can deal with any graphs
- ILP with $O(n^2)$ variables
- Implementations based on TensorFlow



Rotor is efficient, checkmate is general



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Combined ideas

- One network can be divided into several blocks: e.g. GPT-2 \rightarrow Decoder
- Each block is (probably) small enough for checkmate
- Rotor can solve the schedule based on the solutions from checkmate





• Checkmate on PyTorch: obtain the computation graph from any Torch Module

- We can now open the box and generate the forward&backward graph

- Each node in the graph can be executed by a torch function/python code

